# Inverse Problem of Variational Calculus 

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#### Abstract

We will discuss the so-called mixed endpoint conditions for variational problems with non-holonomic constraints given by form actions of order greater than one. We will present some results and discuss the inverse problem of Calculus of Variations.


## 1. Introduction

In the present text we describe new results for the the inverse problem of Variational Calculus for multiple integrals in the context of exterior differential systems. We deal with non-holonomic constraints in the setting of the mixed endpoint conditions defined by P. A. Griffiths ([16]). This work is a follow up of ([29]). In section I and II we present a short review of the latter work. In section III we discuss the inverse problem of Variational Calculus, and conclude in section IV with a study of the Generalized Lagrange Problem with non-holonomic constraints.

Caratheodory [1929], Weil-De Donder [1936] and Lepage [1936-1942] were the first to study Variational Calculus for multiple integrals. Later Dedecker [1953-1977], Liesen [1967], R. Hermann [1966], H. Goldschmidt and S. Sternberg [1973], Ouzilou [1972], D. Krupka [1970-1975], I. M. Anderson [1980], P. L. Garcia and A. Pérez-Rendón [1969-1978], C. Günther [1987], Edelen [1961] and Rund [1966], gave their contributions to this field.

In 1983 Griffiths (see [16]) presented a new approach to variational problems in the context of exterior differential systems. His work in the set of one-dimensional integral manifolds of a differential system $\left(I^{*}, L^{*}\right)$ addressed the problem of finding extrema for the functional $\phi$ using intrinsic

[^0]entities. He established the mixed endpoint conditions for problems with non-holonomic constraints.

The Inverse Problem of Variational Calculus was presented in 1887 by Helmholtz in the following way: given $P_{i}=P_{i}\left(x, u^{j}, u_{x}^{j}, u_{x x}^{j}\right)$ is there a Lagrangian $L\left(x, u^{j}, u_{x}^{j}\right)$ such that $E_{i}(L)=\partial L / \partial u^{i}-D_{x} \partial L / \partial u_{x}^{i}=P_{i}$ where $D_{x}=\partial / \partial x+u_{x}^{i} \partial / \partial u^{i}+u_{x x}^{i} \partial / \partial u_{x}^{i}$ ? He found necessary conditions for $P_{i}$ to be a Euler-Lagrange system (see (3.1) (3.2) and (3.3)). Years later these equations where proved to be locally sufficient conditions.
I. M. Anderson [1992], [1980], P. J. Olver [1986], F. Takens [1979], W. M. Tulczyjew [1980] and A. M. Vinagradov [1964] generalized Helmholtz's conditions both to higher order systems of partial differential equations and to multiple integrals.
1.1. Integral manifolds and valued differential systems. Let X be a manifold and assume that a Pfaffian differential system $\left(I^{*}, L^{*}\right)$ is given by:
i) a subbundle $I^{*} \subset T^{*} X$,
ii) another subbundle $L^{*} \subset T^{*} X$ with $I^{*} \subset L^{*} \subset T^{*} X$,
such that the $\operatorname{rank}\left(L^{*} / I^{*}\right)=n$ (with $n$ being a natural number).
An integral manifold of $\left(I^{*}, L^{*}\right)$ is given by an oriented connected compact $n$-dimensional smooth manifold N (possibly with a piecewise smooth boundary $N$ ) together with a smooth mapping

$$
f: N \rightarrow X
$$

satisfying:

$$
\begin{equation*}
I_{f(x)}^{*}{ }^{\perp}=L_{f(x)}^{*}+f_{*}(T N), \tag{1.1}
\end{equation*}
$$

for all $x \in N$.
$V\left(I^{*}, L^{*}\right)$ is the collection of integral manifolds $f$ of $\left(I^{*}, L^{*}\right)$.
A valued differential system is a triple $\left(I^{*}, L^{*}, \varphi\right)$, where $\left(I^{*}, L^{*}\right)$ is a Pfaffian differential system and $\varphi$ is an n -form on $X$.

We define the functional $\phi$ associated with $\left(I^{*}, L^{*}, \varphi\right)$ in $V\left(I^{*}, L^{*}\right)$ by:

$$
\begin{align*}
& \phi: V\left(I^{*}, L^{*}\right) \rightarrow R, \\
& f \rightarrow \phi[f]=\int f^{*} \varphi . \tag{1.2}
\end{align*}
$$

1.2. Local embeddability. Let us assume that

$$
d\left(C^{\infty}\left(X, L^{*}\right)\right) \subset C^{\infty}\left(X, L^{*} \wedge T^{*} X\right)
$$

and let $d^{\prime}=\operatorname{dim} X, \quad s=\operatorname{rank} I^{*},\left(d\left(C^{\infty}\left(X, L^{*}\right)\right)\right.$ is the set of images by the exterior derivative of $C^{\infty}\left(X, L^{*}\right)$ ). Using the Frobenius theorem, we can set for every $p \in X$ a chart coordinate system $\left\{u^{1}, \ldots, u^{s+n}, v^{1}, \ldots, v^{d^{\prime}-s-n}\right\}$ so that:
i)

$$
\begin{equation*}
\left.L^{*}=\operatorname{span}\left\{d u^{\alpha} \mid 1 \leq \alpha \leq s+n\right\}\right) \tag{1.3}
\end{equation*}
$$

ii)

$$
\begin{equation*}
L^{* \perp}=\operatorname{span}\left\{\left.\frac{\partial}{\partial v^{i}} \right\rvert\, 1 \leq i \leq d^{\prime}-s-n\right\} \tag{1.4}
\end{equation*}
$$

for an open subset $U$ of $X$ with $p \in U$.
Definition 1.1. Let $\left(I^{*}, L^{*}\right)$ be a Pfaffian differential system with

$$
d\left(C^{\infty}(X, L)\right) \subset C^{\infty}\left(X, L^{*} \wedge T^{*} X\right)
$$

$\left(I^{*}, L^{*}\right)$ is locally embeddable if for every $p \in X$ there exists an open neighborhood $U$ of $p$ and local coframes $C F=\left\{\theta_{1}, \ldots, \theta_{s}\right\}$ for $I^{*}$ and $C F^{\prime}=$ $\left\{\theta_{1}, \ldots, \theta_{s}, d u^{s+1}, d u^{s+n}\right\}$ for $L_{U}^{*}$ satisfying the following conditions:
(i) $\left.\delta\left(I_{U}^{*} \wedge \Omega\right) \subset T^{*} U \wedge \wedge^{n}\left(L_{U}^{*}\right) / T^{*} U \wedge I_{U}^{*} \wedge \wedge^{n-1}\left(L^{*}\right)\right)$
(ii) Ker $\delta$ is a constant rank subbundle of $I^{*} \wedge \Omega$,
where $\Omega=\operatorname{span}\left\{d u "^{s+1} \wedge \ldots \wedge \widehat{d u "^{s+\beta}} \wedge \ldots \wedge d u{ }^{s^{s+n}}\right\}, \widehat{d u^{s+\beta}}-$ means deletion of $s+b$ factor (for $n=1, \widehat{d u "^{s+1}}=1$ ).

The map $\delta: I^{*} \wedge \Omega \rightarrow \wedge^{n+1}\left(T^{*} U\right) / I_{u}^{*} \wedge\left(\wedge^{n}\left(T^{*} U\right)\right)$ is induced by:

$$
d: C^{\infty}\left(U, I^{*} \wedge \Omega\right) \rightarrow C^{\infty}\left(U, \wedge^{n+1}\left(T^{*} U\right)\right)
$$

in $I^{*} \wedge \Omega$, i.e, if $I^{*}$ has no Cauchy characteristics, the structure equations are locally:

$$
\begin{equation*}
d \theta^{i} \equiv \pi_{j}^{i} \wedge d u "^{s+j}+A_{i^{\prime} \alpha}^{i j^{\prime}} \pi_{j^{\prime}}^{i^{\prime}} \wedge \theta^{\alpha}+B_{\alpha \beta}^{i} \theta^{\alpha} \wedge d u "^{s+\beta} \bmod I \wedge I \tag{1.5}
\end{equation*}
$$

$1 \leq i, i^{\prime}, \alpha \leq s, 1 \leq j, j^{\prime}, \beta \leq n, I=C^{\infty}\left(X, I^{*}\right)$.
In ([26]) we showed that if $\left(I^{*}, L^{*}\right)$ is locally embeddable, there exist locally defined mappings that induce $\left(I^{*}, L^{*}\right)$ from the canonical system in $J^{1}\left(R^{n}, R^{s}\right)$ with possible constraints, giving a local correspondence between these two differential systems. These sets of systems form a general class that can be described locally by the canonical system of $J^{1}\left(R^{n}, R^{s}\right)$.
1.3. The Cartan system. Let $\left(I^{*}, L^{*}, \varphi\right)$ be a valued differential system on $X$, and $W$ be the total space of $I^{*}$. Let $\chi$ be the canonical form on $T^{*} X$, and $i$ the inclusion map $W \underset{\hookrightarrow}{i} T^{*} X$.

Let us assume that there exists a local $n$-form $\omega$ inducing a nonzero section of $\wedge^{n}\left(L^{*} / I^{*}\right)$ with the following form:

$$
\begin{gather*}
\omega=\omega^{1} \wedge \ldots \wedge \omega^{n}  \tag{1.6}\\
\omega_{i}=(-1)^{i-1} \omega^{1} \wedge \ldots \wedge \widehat{\omega^{i}} \ldots \wedge \omega^{n} \tag{1.7}
\end{gather*}
$$

Let $W^{n}$ be the $n$-Cartesian power of $W$, and $Z$ be a subset of $W^{n}$ defined by $Z=\left\{z \in W^{n}: \pi^{\prime}(z) \in \Delta X^{n}\right\}$, where $\pi^{\prime}$ is the natural projection $\pi^{\prime}(z): W^{n} \rightarrow X$, and $\Delta X^{n}$ is the diagonal submanifold of $X^{n}$.

The subset $Z$ is a vector subbundle over $X$ and $\operatorname{dim} Z=d+s n$ with $d \leq d^{\prime}$. We define

$$
\begin{equation*}
\Psi=d \psi \tag{1.8}
\end{equation*}
$$

where $\psi$ is given by

$$
\begin{equation*}
\psi=\pi^{*} \varphi+\left(\pi^{j} o i^{\prime}\right)^{*}\left[i^{*}(\chi)\right] \wedge \pi^{*} \omega_{j} . \tag{1.9}
\end{equation*}
$$

$\pi^{j}$ is the natural projection into the $j^{\text {th }}$ component $\pi^{j}: W^{n} \rightarrow W$, i ' is the inclusion map $Z \rightarrow W^{n}$ and $\pi$ is the natural projection $\pi: Z \rightarrow X$. Locally $\left(\pi^{j} o i^{\prime}\right)^{*}\left[i^{*}(\chi)\right] \wedge \pi^{*} \omega_{j}=\lambda_{j}^{i} \theta_{i}{ }^{j}$ with $\theta_{i}{ }^{j}=\theta^{j} \wedge \omega_{j}$.

Definition 1.2. Given the $n+1$-form $\Psi$, the Cartan system $C(\Psi)$ is the ideal generated by the set of $n$-forms $\{v\lrcorner \Psi$ where $\left.v \in C^{\infty}(Z, T Z)\right\}$. An integral manifold of $(C(\Psi), \omega)$ is given by an oriented connected compact $n$ dimensional smooth manifold $N$ (possibly with a piecewise smooth boundary $\partial N)$ together with a smooth mapping $f: N \rightarrow X$ satisfying:

$$
\begin{equation*}
f^{*} \theta=0 \quad \text { for every } \quad \theta \in C(\Psi) \tag{1.10}
\end{equation*}
$$

and

$$
\begin{equation*}
f^{*}(\omega) \neq 0 \tag{1.11}
\end{equation*}
$$

Solutions of $(C(\Psi), \omega)$ projected in $X$ will give a candidate for extremum of $\phi$ with suitable boundary conditions.

$$
\begin{equation*}
\left.\left.\delta \phi=\int_{f(N)} v\right\lrcorner d \psi+d(v\lrcorner \psi\right) \tag{1.12}
\end{equation*}
$$

1.4. The momentum space. Suppose we are given on $Z$ :
(i) a closed $(n+1)$-form $\Psi$ with the associated Cartan system $C(\Psi)$,
(ii) $\pi^{\prime *} \omega$ : the pull back to $Z$ of $\omega$, the $n$-form which induces a nonzero section on $\wedge^{n}\left(L^{*} / I^{*}\right)$.
Definition 1.3. Let $\left(C(\Psi), \pi^{* *} \omega\right)_{n}$ be the ideal generated by $\left(C(\Psi), \pi^{* *} \omega\right)$ in $C^{\infty}\left(Z, \wedge^{n} T^{*} Z\right), z_{0} \in Z$ and $E_{0}^{p}$ a $p$-dimensional subspace of the tangent space $T_{z_{0}}$. We say that $\left[z_{0}, E_{0}^{p}\right]$ is a $p$-dimensional integral element of $\left(C(\Psi), \pi^{\prime *} \omega\right)_{n}$ if
(i) $\left\langle E_{0}^{p}, \alpha\right\rangle=0$ for all $\left(C(\Psi), \pi^{\prime *} \omega\right)_{n}$
(ii) $\left.\left\langle E_{0}^{p}\right\lrcorner \omega\right\rangle \neq 0$

The set of integral elements $\left[z_{0}, E_{0}^{n}\right]$ gives a subset

$$
\left.V_{n}\left(C(\Psi), \pi^{*} \omega\right)\right) \subset G_{n}(Z)
$$

Denoting by $\pi$ " the projection $G_{n}(Z) \rightarrow Z$ and assuming regularity at each step, one inductively defines:

$$
\begin{gather*}
\left.\left.Z_{1}=\pi^{\prime \prime}\left(V_{n}\left(C(\Psi), \pi^{*} \omega\right)\right), V_{n}^{\prime}\left(C(\Psi), \pi^{*} \omega\right)\right)\right)= \\
\left\{E \in V_{n}\left(C(\Psi), \pi^{*} \omega\right): E \text { tangent to } Z_{1}\right\}  \tag{1.13}\\
\left.\left.Z_{2}=\pi^{\prime \prime}\left(V_{n}^{\prime}\left(C(\Psi), \pi^{*} \omega\right)\right), V^{\prime \prime}{ }_{n}\left(C(\Psi), \pi^{*} \omega\right)\right)\right)= \\
\left\{E \in V_{n}^{\prime}\left(C\left(\Psi, \pi^{*} \omega\right): E \text { tangent to } Z_{2}\right\} \ldots\right. \tag{1.14}
\end{gather*}
$$

Definition 1.4. $\left(I^{*}, L^{*}, \varphi\right)$ is a locally embeddable valued differential system, and $\omega=\omega^{1} \wedge \ldots \wedge \omega^{n}$. If there exists a $k_{0} \in N$, such that $Z_{k_{0}}=$ $Z_{k_{0}+1}=\ldots=Z_{k_{0}+n^{\prime}}\left(n^{\prime} \in N\right)$ in the above construction, with:
(i) $Z_{k_{0}}$ being a manifold of dimension $(n+1) m+n$ for $m \in N$, and
(ii) $\left(C(\Psi), \pi^{*} \omega\right)_{Z_{k_{0}}}$ being a differential system in $Z_{k_{0}}$ with $r_{n}=0$ (Cartan number in Cartan-Kähler Theorem) for all $\left.V_{n-1}\left(C(\Psi), \pi^{*} \omega\right)\right)$.
Then $\left(I^{*}, L^{*}, \varphi\right)$ is a non-degenerate valued differential system, and $Z=Y$ is called the momentum space.

For $n=1$ we follow [16] and replace condition (ii) by $\psi \wedge \Psi^{n} \neq 0$ on $Z_{k_{0}}$.

We call $\left(C(\Psi), \pi^{*} \omega\right)_{Y}$ the prolongation of $\left(C(\Psi), \pi^{*} \omega\right)$ in the momentum space. By construction, the differential system $\left(C(\Psi), \pi^{*} \omega\right)_{Y}$ satisfies:
(i) the projection $\left(C(\Psi), \pi^{*} \omega\right) \rightarrow Y$ is surjective,
(ii) the integral manifolds of $\left(C(\Psi), \pi^{\prime *} \omega\right)$ on $Z$ coincide with those of $\left(C(\Psi), \pi^{*} \omega\right)$ on $Y$.
1.5. Well-posed valued differential systems. Suppose we have the following subbundles of $T^{*} X$ such that:
(a)

$$
\begin{array}{lllll}
I^{*} & \subset & L^{*} & \subset & T^{*} X  \tag{1.15}\\
\cup & & \cup & & \\
P^{*} & \subset & M^{*}
\end{array}
$$

(b) the locally given $n$-form $\omega$ also induces a nonzero section on $\wedge^{n}\left(M^{*} / P^{*}\right)$,
(c) $\left.Y \subset\left(P^{*}\right)^{n}\right|_{\Delta X^{n}}$, with $Y$ a subbundle of $\left.\left(P^{*}\right)^{n}\right|_{\Delta X^{n}}$.

Definition 1.5. ( $\left.I^{*}, L^{*}, \varphi, P^{*}, M^{*}\right)$ is a well-posed valued differential system if the following conditions are satisfied:
(i) $\left(I^{*}, L^{*}, \varphi\right)$ is a non-degenerate valued differential system (with $\operatorname{dim} Y=(n+1) m+n)$ and $\varphi=L \omega$ for a smooth function $L$ on $X$;
(ii) there exists a subbundle $P^{*}$ of $I^{*}$ of rank $m$ and a subbundle $M^{*}$ of $L^{*}$ of rank $m+n$ as in (1.15);
(iii) $\pi^{* *} M^{*}=\operatorname{span}\left\{\pi^{*} \theta \mid \theta \in C^{\infty}\left(X, M^{*}\right)\right\}$ is completely integrable on $Y$, where $\pi "=\pi \circ i$, and $i$ once more denotes the inclusion mapping $Y \rightarrow Z$ and $\pi$ the projection $Z \rightarrow X$.
$C F=\left\{\theta^{\alpha}, d u^{s+j}, \pi_{j^{\prime}}^{i^{\prime}}, \pi_{j}^{i^{\prime \prime}} \mid 1 \leq \alpha \leq s, 1 \leq i^{\prime} \leq s_{l}, j^{\prime} \in L_{i^{\prime}}, s_{l+1} \leq i^{\prime \prime} \leq\right.$ $s, 1 \leq j \leq n\}$ for $T^{*} X$ with $L_{i^{\prime}} \subset\{k \in N, 1 \leq k \leq n\}$ :
(i)

$$
\begin{equation*}
I^{*}=\operatorname{span}\left\{\theta^{\alpha} \mid 1 \leq \alpha \leq s\right\} ; \tag{1.16}
\end{equation*}
$$

(ii)

$$
\begin{equation*}
L^{*}=\operatorname{span}\left\{\theta^{\alpha}, d u^{s+j} \mid 1 \leq \alpha \leq s, 1 \leq j \leq n\right\} ; \tag{1.1}
\end{equation*}
$$

(iii) $T^{*} X=L^{*} \oplus R^{*}(\oplus$ denotes a direct sum $)$ with $R^{*}=\operatorname{span}\left\{\pi_{j^{\prime}}^{i^{\prime}}, \pi_{j}^{i^{\prime \prime}} \mid 1 \leq\right.$ $\left.i^{\prime} \leq s_{l}, j^{\prime} \in L_{i^{\prime}}, s_{l+1} \leq i^{\prime \prime} \leq s, 1 \leq j \leq n\right\} ;$
(iv)

$$
\begin{equation*}
d \theta_{j^{\prime \prime}}^{i^{\prime}} \equiv 0 \bmod I, \text { for } j^{\prime \prime} \notin L_{i^{\prime}}\left\{\theta_{j^{\prime \prime}}^{i^{\prime}}=\theta^{i^{\prime}} \wedge \omega_{j^{\prime \prime}}\right\} ; \tag{1.18}
\end{equation*}
$$

(v)

$$
\begin{equation*}
d \theta_{j^{\prime}}^{i^{\prime}} \equiv \pi_{j^{\prime}}^{i^{\prime}} \wedge \omega \bmod I, \text { for } j^{\prime} \in L_{i^{\prime}} ; \tag{1.19}
\end{equation*}
$$

(vi)

$$
\begin{equation*}
d \theta_{j}^{i i^{\prime \prime}} \equiv \pi_{j}^{i^{\prime \prime}} \wedge \omega \bmod I, \text { when } 1 \leq j \leq n ; \tag{1.20}
\end{equation*}
$$

(vii) $\pi_{j^{\prime}}^{i^{\prime}}, \pi_{j}^{i^{\prime \prime}}$ are linearly independent $\bmod L$.

In [29] we presented a set of boundary conditions for different types of Well-posed valued differential systems. Solutions of the Cartan system with these boundary conditions have null first variations i.e. they are soutions of the Euler-Lagrange system.

## 2. Generalized Lagrange Problem.

Let $X=J^{1}\left(R^{n}, R^{m}\right)$ (the 1 jet manifold), with the canonical system $I^{*}$ defined on $X$ (i.e. $I^{*}=\operatorname{span}\left\{\theta^{\alpha}=d y^{\alpha}-y_{x^{i}}^{\alpha} d x^{i}\right\}$ ). Let $\varphi=L \omega$ with $\omega=d x^{1} \wedge \ldots \wedge d x^{n}$. We choose $x^{1}, \ldots, x^{n}$ to be coordinates for $R^{n}$, and $y^{1}, \ldots, y^{m}$ coordinates for $R^{m}$.
Definition 2.1. Let $f$ be a solution to the canonical differential system $I^{*}$, with the independence condition given by $L^{*}=\operatorname{span}\left\{I^{*}, d x^{1}, \ldots, d x^{n}\right\}$ and $k \in N$. The family $F\left(x, t_{1}, \ldots, t_{k}\right)$ of integral manifolds of $\left(I^{*}, L^{*}\right)$ is a $k$-parameter variation of $f$ if:
(i) $F\left(x, t_{1}, \ldots, t_{k}\right)$ is smooth with $\left(t_{1}, \ldots, t_{k}\right) \in\left[0, \epsilon_{1}\right] \times \ldots \times\left[0, \epsilon_{k}\right]$, for $\epsilon_{i}>0,1 \leq i \leq k$,
(ii) $F_{\left(t_{1}, \ldots, t_{k}\right)} \doteq \bar{F}\left(x, t_{1}, \ldots, t_{k}\right) \in V\left(I^{*}, L^{*}\right)$ for all $\left(t_{1}, \ldots, t_{k}\right) \in\left[0, \epsilon_{1}\right] \times$ $\ldots \times\left[0, \epsilon_{k}\right]$,
(iii) $F(x, 0)=f(x)$ for all $x \in N, N \subset R$.
$F_{*}\left(\frac{\partial}{\partial t_{i}}\right)$ is an infinitesimal variation of $F$.
We will consider variations satisfying the condition $\pi "(F(x, t))=\pi "(f(x))$ for all $x \in \partial N$ and $t \in[0, \epsilon] \quad\left(\pi^{\prime \prime}\right.$ is the projection $\left.J^{1}\left(R^{n}, R^{m}\right) \rightarrow R^{n}\right)$.

Without loss of generality we can choose $v$ so that $v\lrcorner d x^{i}=0$, thus replacing a one parameter variation of $f$ by another that has the same first and second variation while satisfying:

$$
\begin{equation*}
\pi^{\prime \prime}(F(x, t))_{N}=i d_{N} \tag{2.1}
\end{equation*}
$$

for all $t \in[0, \epsilon])$.
The framework of this Lagrange problem subjected to constrains represents a very important set of problems for the study of Calculus of Variations.

## 3. Inverse problem for calculus of variations.

3.1. Two Examples. In 1887, Helmholtz solved the following problem:

Example 1. Given $P_{i}=P_{i}\left(x, u^{j}, u_{x}^{j}, u_{x x}^{j}\right)$. Is there a Lagrangian $L\left(x, u^{j}, u_{x}^{j}\right)$ such that $E_{i}(L)=\partial L / \partial u^{i}-D_{x} \partial L / \partial u_{x}^{i}=P_{i}$ where $D_{x}=$ $\partial / \partial x+u_{x}^{i} \partial / \partial u^{i}+u_{x x}^{i} \partial / \partial u_{x}^{i}$ ? He found the necessary conditions for $P_{i}$ :
(i)

$$
\begin{equation*}
\partial P_{i} / \partial u_{x x}^{j}=\partial P_{j} / \partial u_{x x}^{i}, \tag{3.1}
\end{equation*}
$$

(ii)

$$
\begin{equation*}
\partial P_{i} / \partial u_{x}^{j}=\partial P_{j} / \partial u_{x}^{i}+2 D_{x} \partial P_{j} / \partial u_{x x}^{i}, \tag{3.2}
\end{equation*}
$$

(iii)

$$
\begin{equation*}
\partial P_{i} / \partial u^{j}=\partial P_{j} / \partial u^{i}-D_{x} \partial P_{j} / \partial u_{x}^{i}+D_{x x} \partial P_{j} / \partial u_{x x}^{i} . \tag{3.3}
\end{equation*}
$$

This problem led to the following studies [4].
(i) - the derivation and analysis of Helmholtz conditions as necessary and (locally) sufficient conditions for a differential operator to coincide with the Euler-Lagrange operator for some Lagrangian;
ii) - the characterization of the obstructions to the existence of global variational principles for different operators defined on manifolds;
iii) - the invariant inverse problem for different operators with symmetry; and
(iv) - the variational multiplier problem wherein variational principles are found, not for a given differential operator, but rather for the differential equations determined by that operator.

That is: find a matrix $B=\left[B_{i}^{j}\right]$ such that $B_{i}^{j} P_{j}=E_{i}(L)$ for some $L$, with $B$ being non-singular.

Let $E \rightarrow M$ be a fibered manifold. $J^{\infty}(E)$ is the infinite jet of $E$.
Let

$$
\begin{gather*}
\theta^{i}=d u^{i}-u_{x}^{i} d x  \tag{3.4}\\
\theta_{x}^{i}=d u_{x}^{i}-u_{x x}^{i} d x \tag{3.5}
\end{gather*}
$$

and

$$
\begin{align*}
& \Omega_{P}=P_{i} \theta^{i} \wedge d x+1 / 2\left[\partial P_{i} / \partial u_{x}^{i}-D_{x} \partial P_{i} / \partial u_{x x}^{i}\right] \theta^{i} \wedge \theta^{j} \\
&+1 / 2\left[\partial P_{i} / \partial u_{x x}^{i}+\partial P_{j} / \partial u_{x x}^{i}\right] \theta^{i} \wedge \theta_{x}^{j} . \tag{3.6}
\end{align*}
$$

If $P$ satisfies the Helmholtz conditions, then $d \Omega_{P}=0$. If $\Omega_{P}$ is exact (equivalently if $H^{n+1}(E) \mathrm{n}+1$ de Rham cohomology group of E is trivial), then $P_{i}$ is globally variational.

If $\theta_{L}=L d x+\partial L / \partial u_{x}^{i} \theta^{i}$, then $d \theta_{L}=\Omega_{P}$.
In 1913, Volterra [50] showed that if $L=\int_{N} u^{i} P_{i}\left(x, t u^{j}, t u_{x}^{j}, t u_{x x}^{j}\right) d t$ where $N=[0,1]$, then:

$$
\begin{equation*}
E_{i}(L)=P_{i} . \tag{3.7}
\end{equation*}
$$

We have a global solution to the inverse problem in the case of one independent variable and to equations $P_{i}=0$ of second order.

Vaingberg 1964 [49] generalized this result, however this Lagrangian is usually of much higher order than necessary.

From [5] one can derive the following theorem:
Theorem 3.1. Let $\Delta$ be a differential operator of order $2 k$

$$
\begin{equation*}
\Delta=P_{\beta}\left(x^{i}, u^{j}, u_{1}^{j}, \ldots, u_{2 k}^{j}\right) \theta^{\beta} \wedge \omega . \tag{3.8}
\end{equation*}
$$

Then $\Delta$ is the Euler-Lagrange operator of $a k-t h$ order Lagrangian $L=$ $L\left(x^{i}, u^{j}, u_{1}^{j}, \ldots, u_{k}^{j}\right)$, if and only if $\Delta$ satifies the higher order Helmholtz conditions, and the functions

$$
\begin{equation*}
p_{\beta}(t)=P_{\beta}\left(x^{i}, u^{j}, u_{1}^{j}, \ldots, u_{k}^{j}, t u_{k+1}^{j} \ldots, t^{k} u_{2 k}^{j}\right) \tag{3.9}
\end{equation*}
$$

are polynomials in $t$ of degree less or equal to $k$.
The functions $u_{k}^{j}$ denote all possible $k^{\text {th }}$-order derivatives of $u^{j}, 1 \leq$ $\beta, j \leq m$ and $1 \leq i \leq n, \theta^{\beta}=d y^{\beta}-y_{x^{i}}^{\beta} d x^{i}$ and $\omega=d x^{1} \wedge \ldots \wedge d x^{n}$.
Example 2. Let $T=T\left(x, y, z, u, u_{x}, u_{y}, u_{z}, u_{x x}, u_{x y}, \ldots, u_{z z}\right)$ be a second order operator. We assume that $T$ is a smooth function.
Let $L=L\left(x, y, z, u, u_{x}, u_{y}, u_{z}\right)$ be a first-order operator with $L$ being a smooth function.

$$
E[L]=\partial L / \partial u-D_{x} \partial L / \partial u_{x}-D_{y} \partial L / \partial u_{y}-D_{z} \partial L / \partial u_{z}
$$

where

$$
D_{x}=\partial / \partial x+u_{x} \partial / \partial u+u_{x x} \partial / \partial u_{x}+u_{x y} \partial / \partial u_{y}+\ldots
$$

Let $v$ be a lift to the momentum space of an infinitesimal variation $F_{*}(\partial / \partial t)$ of $f=\pi o g$, where $g$ is a solution of $\left(C(\Psi), \pi^{*} \omega\right)$. The Liederivative of $\psi=\pi^{*} \varphi+\left(\pi^{j} o i^{\prime}\right)^{*}\left[i^{*}(\chi)\right] \wedge \pi^{*} \omega_{j}$ along $v$ is:

$$
\begin{gather*}
v\lrcorner d \psi+d(v\lrcorner \psi)=E[L](u) v^{1} \pi^{*}(d x \wedge d y \wedge d z) \\
+d\left(\partial L / \partial u_{x} v^{1} \pi^{*}(d y \wedge d z)-\partial L / \partial u_{y} v^{1} \pi^{*}(d x \wedge d z)\right. \\
\left.+\partial L / \partial u_{z} v^{1} \pi^{*}(d x \wedge d y)\right) \tag{3.10}
\end{gather*}
$$

Suppose that for every vector $v$ with $\pi_{*} v \in T_{f} V\left(I^{*}, L^{*}, \varphi,[h]\right)$ we have a vector $w$ with $\pi_{*} w \in T_{f} V\left(I^{*}, L^{*}, \varphi,[h]\right)$ such that

$$
\begin{gather*}
v\lrcorner d \psi+d(v\lrcorner \psi)=T[u] v^{1} \pi^{*}(d x \wedge d y \wedge d z) \\
+d\left(\partial L / \partial u_{x} w^{1} \pi^{*}(d y \wedge d z)-\partial L / \partial u_{y} w^{1} \pi^{*}(d x \wedge d z)\right. \\
\left.+\partial L / \partial u_{z} w^{1} \pi^{*}(d x \wedge d y)\right) . \tag{3.11}
\end{gather*}
$$

Then we have $T[u]=E[L](u)$.
If we identify $e_{1}$ with $\pi^{*}(d y \wedge d z), e_{2}$ with $\pi^{*}(d z \wedge d y)$ and $e_{3}$ with $\pi^{*}(d x \wedge d y)$ at each point of the integral manifold of $\left(C(\Psi), \pi^{*} \omega\right)$, we can write:

$$
d\left(\partial L / \partial u_{x} v^{1} \pi^{*}(d y \wedge d z)-\partial L / \partial u_{y} v^{1} \pi^{*}(d x \wedge d z)+\partial L / \partial u_{z} v^{1} \pi^{*}(d x \wedge d y)\right)
$$

$$
=\operatorname{Div} V[u] \pi^{*}(d x \wedge d y \wedge d z)
$$

where

$$
\begin{equation*}
V[u]=\partial L / \partial u_{x} v^{1} e_{1}+\partial L / \partial u_{y} v^{1} e_{2}+\partial L / \partial u_{z} v^{1} e_{3} \tag{3.12}
\end{equation*}
$$

We can conclude that

$$
v\lrcorner d \psi+d(v\lrcorner \psi)=(E[L](u) v+\operatorname{Div} V[u]) \pi^{*}(d x \wedge d y \wedge d z)
$$

We have

$$
\begin{equation*}
E[L](u)=0 \quad \text { if } \quad L[u]=\operatorname{Div} W[u] \tag{3.13}
\end{equation*}
$$

Suppose $T[u]=E[L](u)$. Then

$$
E(E[L](u) v+\operatorname{Div} V[u])=E[T(u) v]
$$

Let

$$
\begin{equation*}
\psi^{\prime}=\pi^{*} T \omega+\left(\pi^{j} o i^{\prime}\right)^{*}[i *(\chi)] \pi^{*} \omega_{j} \tag{3.14}
\end{equation*}
$$

If we define

$$
\left.\left.H(T)[v] \pi^{*}(d x \wedge d y \wedge d z)=v\right\lrcorner d \psi^{\prime}+d(v\lrcorner \psi^{\prime}\right)-E[T(u) v] \pi^{*}(d x \wedge d y \wedge d z)
$$

then $H(T)=0$ if $T[u]$ is Euler-Lagrange. Helmholtz equations are:
(i) $\partial T / \partial u_{x}=D_{x} \partial T / \partial u_{x x}+1 / 2 D_{y} \partial T / \partial u_{x y}+1 / 2 D_{z} \partial T / \partial u_{x z}$,
(ii) $\partial T / \partial u_{y}=D_{y} \partial T / \partial u_{x x}+1 / 2 D_{x} \partial T / \partial u_{y x}+1 / 2 D_{z} \partial T / \partial u_{y z}$,
(iii) $\partial T / \partial u_{z}=D_{z} \partial T / \partial u_{x x}+1 / 2 D_{x} \partial T / \partial u_{z x}+1 / 2 D_{y} \partial T / \partial u z z$.

We have a sequence of spaces

$$
\begin{equation*}
0 \rightarrow R \rightarrow F[u] \xrightarrow{\text { Grad }} V(u) \xrightarrow{\text { Curl }} V(u) \xrightarrow{\text { Div }} F(u) \xrightarrow{E} F(u) \xrightarrow{H} V(u) \tag{3.15}
\end{equation*}
$$

that is a cochain complex, the Euler-Lagrange complex, where $F[u]$ is the set of smooth functions $F\left(x, y, z, u, u_{x}, u_{y}, u_{z}, u_{x x}, u_{x y}, \ldots, u_{z z}\right), V[u]$ is the set of vector fields defined in $R^{n}$ with $F[u]$ coeficients. This complex is exact and thus the inverse problem is solved in this second example.
3.2. Variational Bicomplex. Let us introduce now a very important tool for a globalization of the inverse problem [40].
Definition 3.1. A p form $\omega$ on $J^{\infty}(E)$ is said to be of type $(r, s)$, where $r+s=p$, if at each point $x$ of $J^{\infty}(E)$,

$$
\begin{equation*}
\omega\left(X_{1}, X_{2}, \ldots, X_{p}\right)=0 \tag{3.16}
\end{equation*}
$$

whenever either
(i) more than $s$ of the vectors $X_{1}, X_{2}, \ldots, X_{p}$ are $\pi_{M}^{\infty}$ vertical, or
(ii) more than $r$ of the vectors $X_{1}, X_{2}, \ldots, X_{p}$ annihilate all contact one forms.

Note: $\Omega^{r, s}$ denotes the space of type $(r, s)$ forms on $J^{\infty}(E)$.
(i) $\pi: E \rightarrow M$ is a fiber bundle.
(ii) In some cases we can assume that there exists a transformation group $G$ acting on $E$.
(iii) There exists a set of differential equations on sections of $E$.

$$
\begin{gather*}
d=d_{H}+d_{V} \\
d_{H}: \Omega^{r, s}\left(J^{\infty}(E)\right) \rightarrow \Omega^{r+1, s}\left(J^{\infty}(E)\right),  \tag{3.17}\\
d_{V}: \Omega^{r, s}\left(J^{\infty}(E)\right) \rightarrow \Omega^{r, s+1}\left(J^{\infty}(E)\right)  \tag{3.18}\\
d_{H}^{2}=0, d_{H} d_{V}=-d_{V} d_{H}, d_{V}^{2}=0 \tag{3.19}
\end{gather*}
$$

In local coordinates

$$
\begin{gather*}
d_{H} f=\left[\partial f / \partial x^{i}+u \alpha_{i} \partial f / \partial u^{\alpha}+u_{i j}^{\alpha} \partial f / \partial u_{j}^{\alpha}+\ldots\right] d x^{i}  \tag{3.20}\\
d_{V} f=\partial f / \partial u^{\alpha} \theta^{\alpha}+\partial f / \partial u_{i}^{\alpha} \theta_{i}^{\alpha}+\ldots \tag{3.21}
\end{gather*}
$$

I is locally given by:

$$
\begin{gather*}
\left.\left.I=\Omega^{r, s}\left(J^{\infty}(E)\right)\right) \rightarrow \Omega^{r, s}\left(J^{\infty}(E)\right)\right)  \tag{3.22}\\
\left.I(\omega)=\frac{1}{s} \theta^{\alpha} \wedge\left[\left(\partial / \partial u^{\alpha}\right\lrcorner \omega\right)-D_{i}\left(\left(\partial / \partial u_{i}^{\alpha}\right\lrcorner \omega\right)+D_{i j}\left(\left(\partial / \partial u_{i j}^{\alpha}\right\lrcorner \omega\right)-\ldots\right] \tag{3.23}
\end{gather*}
$$

Definition 3.2. The sequences of spaces

$$
\begin{align*}
& 0 \rightarrow R \quad \rightarrow \Omega^{0,0} \quad \xrightarrow{d_{H}} \Omega^{1,0} \quad \xrightarrow{d_{H}} \Omega^{2,0} \quad \ldots \xrightarrow{d_{H}} \Omega^{n-1,0} \quad \xrightarrow{d_{H}} \Omega^{n, 0} \tag{3.24}
\end{align*}
$$

is the Variational Bicomplex.
Therefore the generalization of (3.15) is:

$$
\begin{equation*}
0 \rightarrow R \rightarrow \Omega^{0,0} \xrightarrow{d_{H}} \Omega^{1,0} \xrightarrow{d_{H}} \Omega^{2,0} \ldots \xrightarrow{d_{H}} \Omega^{n-1,0} \xrightarrow{d_{H}} \Omega^{n, 0} \xrightarrow{E} F^{1} \xrightarrow{\delta_{H}} F^{2} \xrightarrow{\delta_{H}} F^{3} \ldots \tag{3.25}
\end{equation*}
$$

## 4. G.L. Problem with non-holonomic constraints

4.1. G.L. Problem with non-holonomic constraints. Let us recall from [26] the Generalized Lagrange problem with non-holonomic constraints for $n>1, m=1$.

Let us assume $g^{\rho}\left(x^{i}, u, u_{x^{j}}\right)=0$, with $\operatorname{rank}\left[\partial g^{\rho} / \partial u_{x^{j}}\right]=n-l$, $g^{\rho}\left(x^{i}, u, u_{x^{j}}\right)$ smooth functions with $1 \leq j \leq n, 1 \leq \rho \leq n-l$ and $l \geq 0$ $\left(I^{*}, L^{*}, \varphi, I^{*}, L^{*}\right)$ is a well-posed valued differential system, where: $I^{*}=$ $\operatorname{span}\{\theta\}$, and $L^{*}=\operatorname{span}\left\{\theta, d x^{i} \mid 1 \leq i \leq n\right\}$

$$
\begin{equation*}
\theta=\left\{d u-u_{x^{i}} d x^{i} \mid 1 \leq i \leq n\right\} . \tag{4.1}
\end{equation*}
$$

In this setting we have:

$$
\begin{gather*}
d \theta_{\mu}=-d u_{x^{\mu}} \wedge \omega  \tag{4.2}\\
d \theta_{\rho}=-\left(A_{\rho}^{\mu} d u_{x^{\mu}} \wedge \omega-B_{\rho} \theta \wedge \omega\right)  \tag{4.3}\\
A_{\rho}^{\mu}=-a_{\sigma}^{\rho} g_{u_{x^{\mu}}}^{\sigma}  \tag{4.4}\\
B_{\rho}=-a_{\sigma}^{\rho} g_{u}^{\sigma}  \tag{4.5}\\
L^{\mu}=\left(\partial / \partial d u_{x^{\mu}}-A_{\rho}^{\mu} \partial / \partial u_{x^{\rho}}\right) L,  \tag{4.6}\\
L^{\mu \nu}=\left(\partial / \partial d u_{x^{\mu}}-A_{\rho}^{\mu} \partial / \partial u_{x^{\rho}}\right) L^{\nu}, \tag{4.7}
\end{gather*}
$$

and

$$
\begin{gather*}
{\left[a_{\sigma}^{\rho}\right]=\left[g_{u_{\rho}}^{\sigma}\right]^{-1} \text { with } 1 \leq \rho, \sigma, \leq n-l \text { and } n-l+1 \leq \mu, \nu \leq n}  \tag{4.8}\\
\begin{array}{c}
\Psi \equiv\left(L^{\mu}-\lambda^{\mu}-\lambda^{\rho} A_{\rho}^{\mu}\right) \pi^{*}\left(d u_{x^{\mu}} \wedge \omega\right)+d \lambda^{\mu} \wedge \pi^{*}\left(\theta_{\mu}\right)+d \lambda^{\rho} \wedge \pi^{*}\left(\theta_{\rho}\right) \\
\\
+\left(L_{u}-\lambda^{\rho} B_{\rho}+L_{u_{x} \rho} B_{\rho}\right) \pi^{*}(\theta \wedge \omega)
\end{array}
\end{gather*}
$$

The Cartan system is:

$$
\begin{gather*}
\pi^{*} \theta_{\alpha} \quad(1 \leq \alpha \leq n)  \tag{4.10}\\
\left(L^{\mu}-\lambda^{\mu}-\lambda^{\rho} A_{\rho}^{\mu}\right) \pi^{*} \omega \quad(n-l+1 \leq \mu \leq n)  \tag{4.11}\\
\left(-d \lambda^{\rho} \wedge \pi^{*} \omega_{\rho}-d \lambda^{\mu} \wedge \pi^{*} \omega_{\mu}\right)+\left(L_{u}+\lambda^{\rho} B_{\rho}-L_{u_{x} \rho} B_{\rho}\right) \wedge \pi^{*} \omega \tag{4.12}
\end{gather*}
$$

Let us assume $g^{\rho} / \partial u_{x^{\mu}}=0$ for all $n-l+1 \leq \mu \leq n$ and all $1 \leq \rho \leq n-l$. Then the Euler-Lagrange equation is:

$$
\begin{equation*}
E[L]=\partial L / \partial u+\partial L / \partial u_{x^{\sigma}} B_{\sigma}-D_{x^{\mu}} \partial L / \partial u_{x^{\mu}}+\lambda^{\sigma} B_{\sigma}-\lambda_{x^{\rho}}^{\rho} \tag{4.13}
\end{equation*}
$$

Proposition 4.1. Let $\left(I^{*}, L^{*}\right)$ be a locally embeddable differential system defined in $X=\left.J^{1}\left(R^{n}, R\right)\right|_{g^{\rho}\left(x^{i}, u, u_{x^{j}}\right)=0}, \operatorname{rank}\left[\partial g^{\rho} / \partial u_{x^{j}}\right]=n-l$, $g^{\rho}\left(x^{i}, u, u_{x^{j}}\right)$ smooth functions, $1 \leq i, j \leq n, 1 \leq \rho \leq n-l, l \geq 0$, and $g^{\rho} / \partial u_{x^{\mu}}=0$ for all $n-l+1 \leq \mu \leq n$ and all $1 \leq \rho \leq n-l$, where $I^{*}=$ span $\{\theta\}$, $L^{*}=\operatorname{span}\left\{\theta, d x^{i} \mid 1 \leq i \leq n\right\}$,

$$
\begin{equation*}
\theta=d u-u_{x^{j}} d x^{j} \quad 1 \leq j \leq n \tag{4.14}
\end{equation*}
$$

Let $Q\left(x^{i}, u, u_{x^{\mu}}, u_{x^{\mu} x^{\nu}}, \lambda^{\rho}, \lambda_{x^{i}}^{\rho}\right)$ with $n-l+1 \leq \mu, \nu \leq n, 1 \leq \sigma, \rho \leq n-l$ and $1 \leq i \leq n$, with $Q\left(x^{i}, u, u_{x^{\mu}}, t u_{x^{\mu} x^{\nu}}, \lambda^{\rho}, \lambda_{x^{i}}^{\rho}\right)$ being a polynomial in $t$ of degree less or equal to 1 , and

$$
\begin{equation*}
P=Q+\lambda_{x^{\rho}}^{\rho}-\lambda^{\rho} B_{\rho} . \tag{4.15}
\end{equation*}
$$

And furthermore, let us assume that $P$ satisfies the Helmholtz conditions and does not depend on $\lambda_{\rho}$ and $\lambda_{x^{i}}^{\rho}$ coordinates, then $Q$ is locally a EulerLagrange operator for a Lagrangian $L\left(x^{i}, u, u_{x^{\mu}}\right)$.

Proof: In this case the Helmholtz condition is:

$$
\begin{equation*}
\partial P / \partial u_{x^{\mu}}=D_{x^{\mu}} \partial P / \partial u_{x^{\mu} x^{\mu}}+1 / 2 D_{x^{\nu}} \partial P / \partial u_{x^{\mu} x^{\nu}} \tag{4.16}
\end{equation*}
$$

with $n-l+1 \leq \mu, \nu \leq n$.
From Theorem 3.1 we know that a function $F\left(x^{i}, u, u_{x^{\mu}}\right)$ can be found that does not depend on $u_{x x}^{\nu}$, such that $E[F]=\partial F / \partial u-D_{x}^{i} \partial F / \partial u_{x}^{i}$.

In addition, if in the domain of $P$ the sequence of spaces is exact:

$$
\begin{equation*}
\Omega^{n, 0} \xrightarrow{E} F^{1} \xrightarrow{H} 0 \tag{4.17}
\end{equation*}
$$

then we have a global solution for the inverse problem.
Example 3. Let $X=\left.J^{1}\left(R^{n}, R\right)\right|_{g^{\rho}\left(x^{i}, u, u_{x^{j}}\right)=0}, \operatorname{rank}\left[\partial g^{\rho} / \partial u_{x^{j}}\right]=n-l$, $g^{\rho}\left(x^{i}, u, u_{x^{j}}\right)$ smooth functions, $1 \leq i, j \leq n, 1 \leq \rho \leq n-l, l \geq 0$, and $g^{\rho} / \partial u_{x^{\mu}}=0$ for all $n-l+1 \leq \mu \leq n$ and all $1 \leq \rho \leq n-l$, where $I^{*}=\operatorname{span}\{\theta\}, L^{*}=\operatorname{span}\left\{\theta, d x^{i} \mid 1 \leq i \leq n\right\}$ and $Q\left(x^{i}, u, u_{x^{\mu}}, u_{x^{\mu} x^{\nu}}\right)=$ $2 u_{x^{\sigma}}\left(x^{i}, u\right) B_{\sigma}-\sum_{\mu} 2 u_{x^{\mu} x^{\mu}}+\lambda^{\sigma} B_{\sigma}-\lambda_{x^{\rho}}^{\rho} . Q$ satisfies Helmhotz equations and is globally a Euler-Lagrange operator with $L=\sum_{\mu}\left(u_{x^{\mu}}\right)^{2}+\sum_{\sigma}\left(u_{x^{\sigma}}\left(x^{i}, u\right)\right)^{2}$.

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